

Token based Protocols



Token Passing:

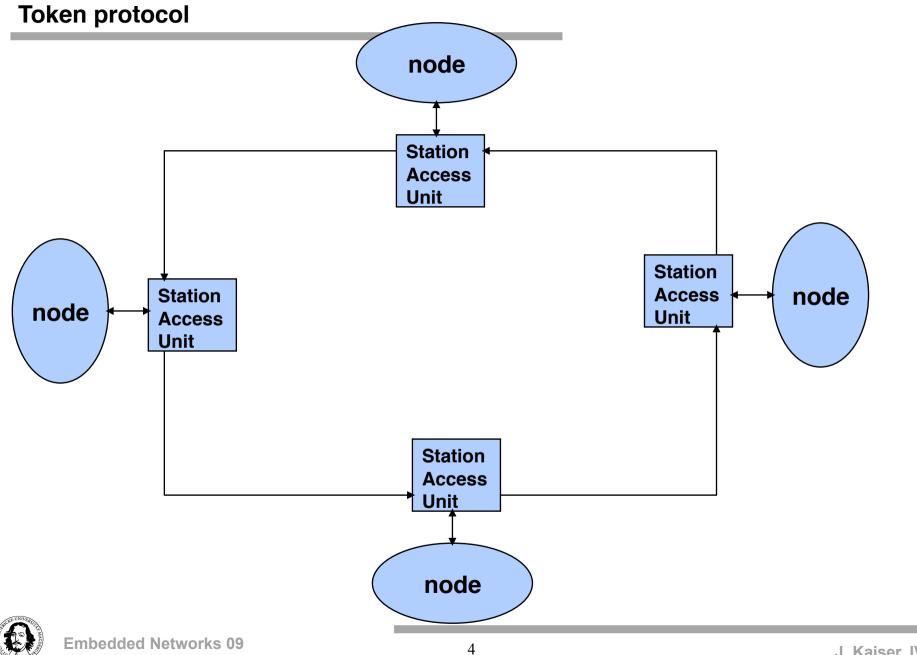
Multiple Masters circulate a token.

Token Ring: physical ring (IEEE 802.5) Token Bus: logical ring (IEEE 802.4)

Delegated Token:	
connection oriented:	Central busarbiter grants a token to a participant to send one or more messages.
message oriented:	The central busarbiter requests a participant to send a message by sending the token to this participant. Centrally controlled message dissemination.
Examples: Connecti	ion oriented: Profibus (Token Passing (logical Ring)

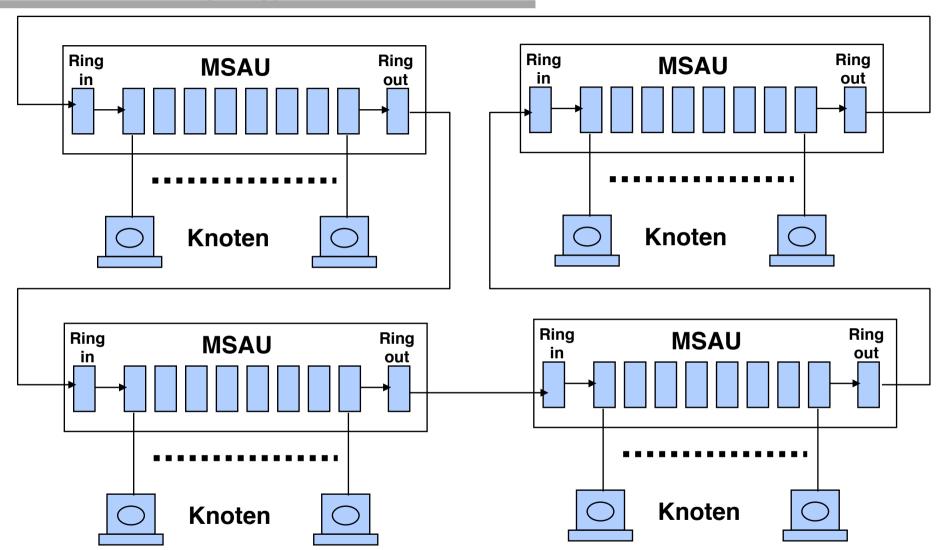
message oriented: FIP (Factory Instrumentation Protocol)





J. Kaiser, IVS-EOS

Token network topology



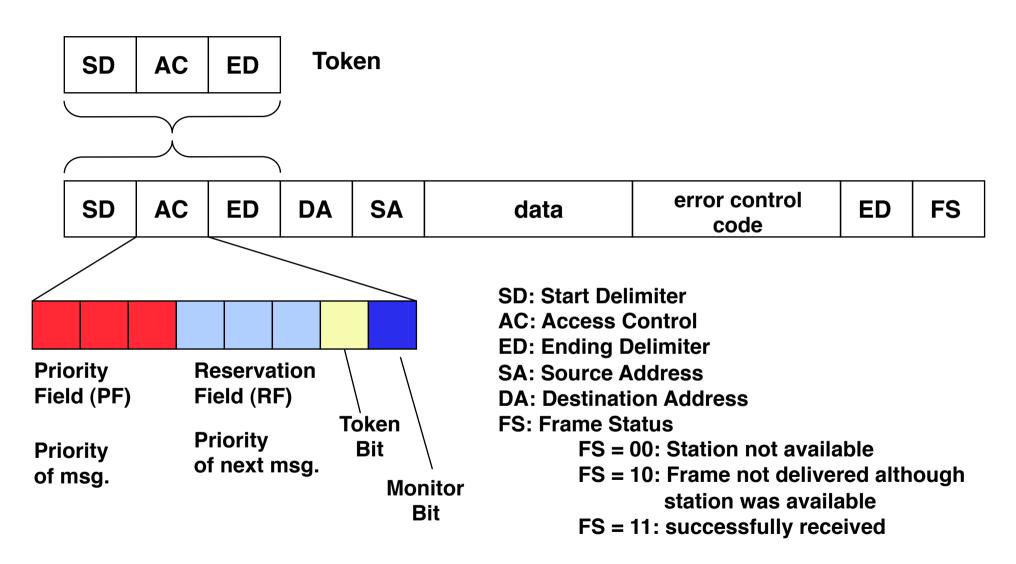
MSAU: Multi Station Access Unit

5

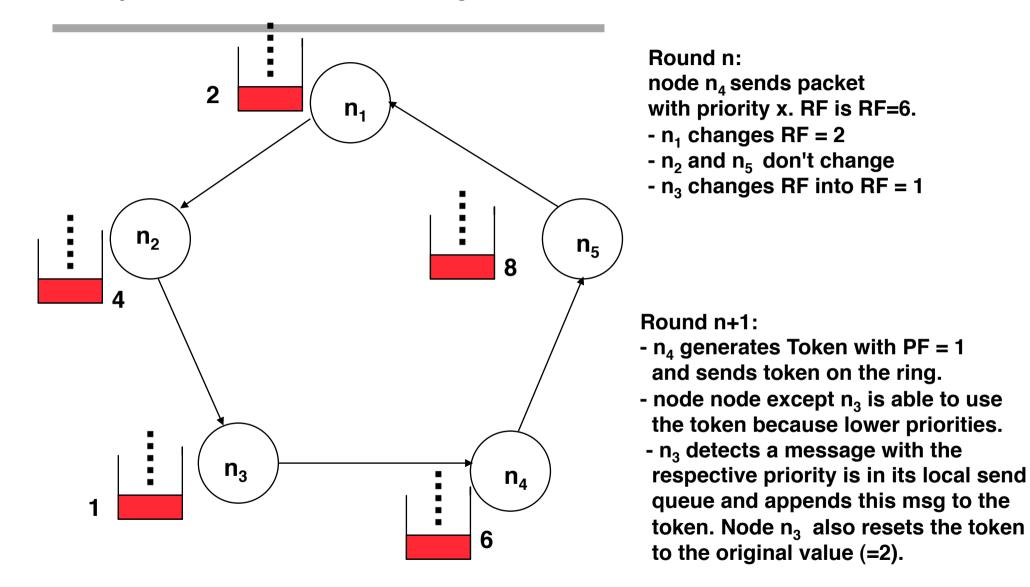


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802.5 Token Ring Frame Format



Priority based reservation of messages



Priority System

Token Ring networks use a sophisticated priority system that permits certain user-designated, high-priority stations to use the network more frequently. Token Ring frames have two fields that control priority: the *priority* field and the *reservation* field.

Only stations with a priority equal to or higher than the priority value contained in a token can seize that token. After the token is seized and changed to an information frame, only stations with a priority value higher than that of the transmitting station can reserve the token for the next pass around the network.

When the next token is generated, it includes the higher priority of the reserving station. Stations that raise a token's priority level must reinstate the previous priority after their transmission is complete.



Predictability of various Networks*

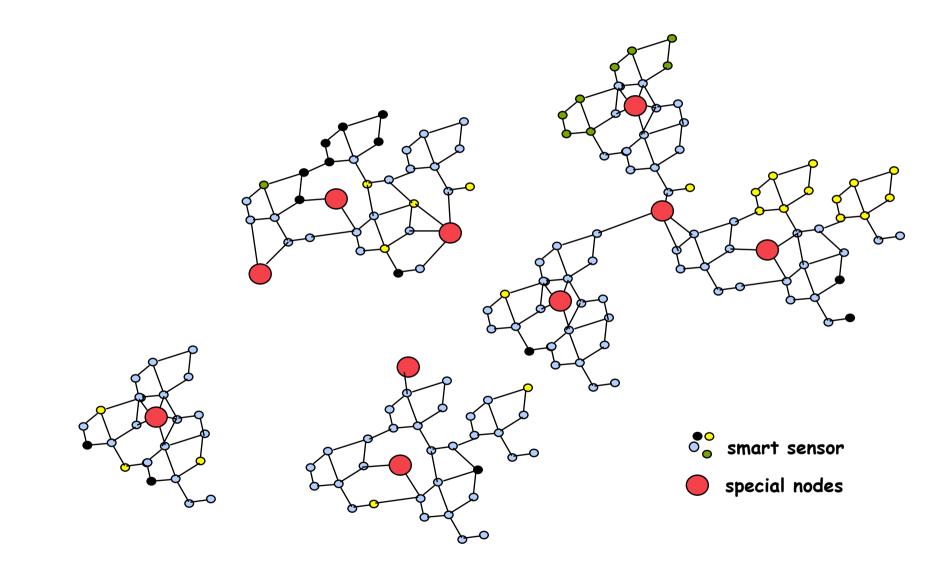
Worst Case Times of Inaccessit	oility* t _{inacc} (ms)	_
ISO 8002/4 Token Bus (5 Mbps)	139.99	Token-based Protocols
ISO 8002/5 Token Ring (4 Mbps)	28278.30	
ISO 9314 FDDI (100 Mbps)	9457.33	Protocois
Profibus (500 kbps)	74.80	- .
CSMA/CD	unbounded	
CSMA/CA	stochastic	CSMA Protocols
CAN-Bus (1Mbps)	2.48	

The worst-case-delay of the Timed-Token-Protocol** is 2•TTRT (Target Token Rotating Time)

* P. Verissimo, J. Ruffino, L. Ming:" How hard is hard real-time communication on field-busses?"



Sensornets for a wired physical world



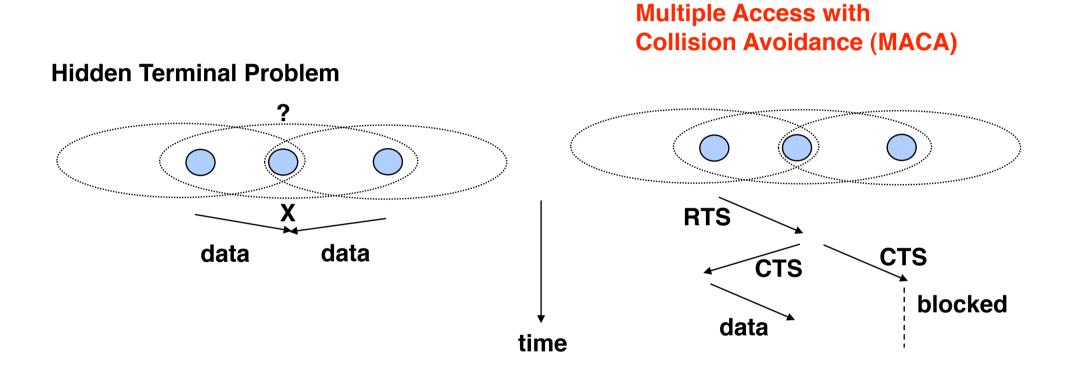


 $\frac{3}{3}$

	trigger to send	Start time	channels
(simple) Aloha	data availability	arbitrary	1
Slotted Aloha	time slots	start of a time slot	1
MACA	RTS/CTS	dyn. reservation	1
MACAW	MACA + Acknowledge	same as MACA	1
CSMA	medium free	arbitrary	1
CSMA/CA	medium free	after waiting time or dyn. reserv.	1
TDMA	acc.schedule	preplanned	1
FDMA	multiple frequencies	arbitrary	m
CDMA	orthogonal codes	arbitrary	m



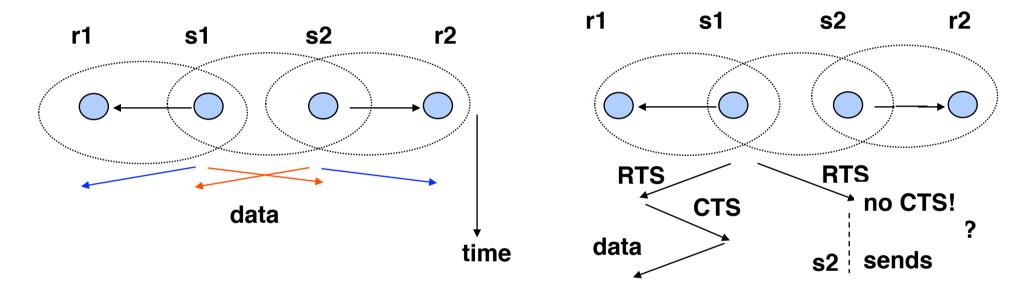
Problems



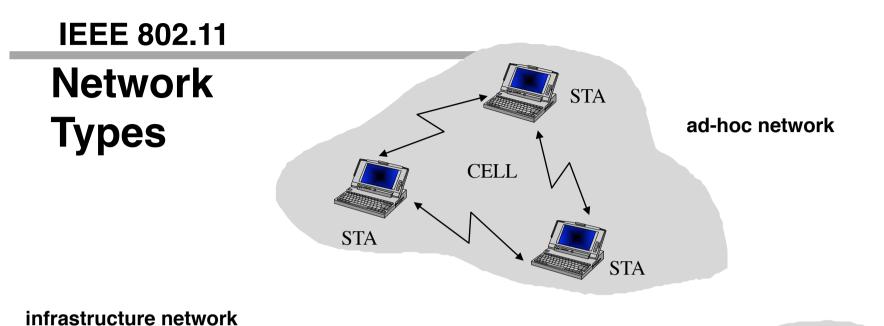


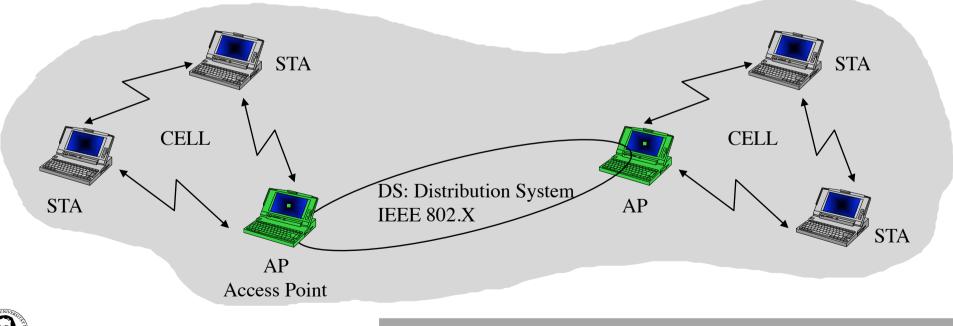
More problems

Exposed Terminal Problem



RTS/CTS to improve throughput

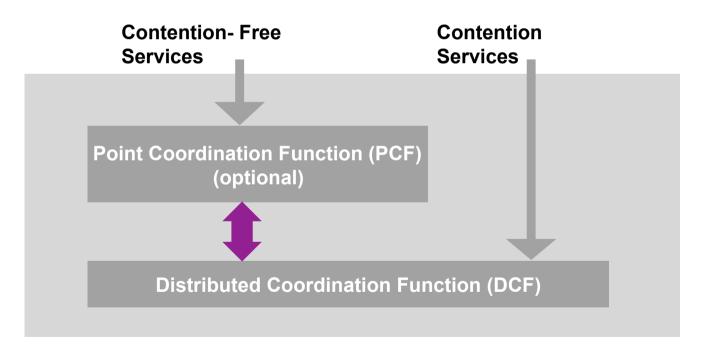






IEEE 802.11 MAC Layer

MAC Architektur:

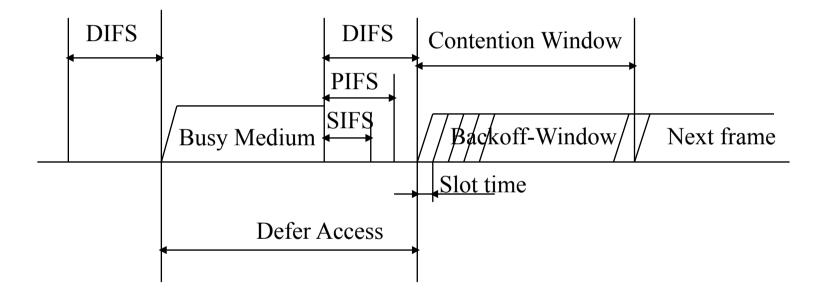


Distributed Coordination Function (DCF)

- CSMA/CA Protocol
- Collision Avoidance by random backoff procedure (p-persistent)
- All Frames are acknowledged, lost Frames are resend
- Priority Access by Interframe Space (IFS)
- => fair arbitration but no real-time support

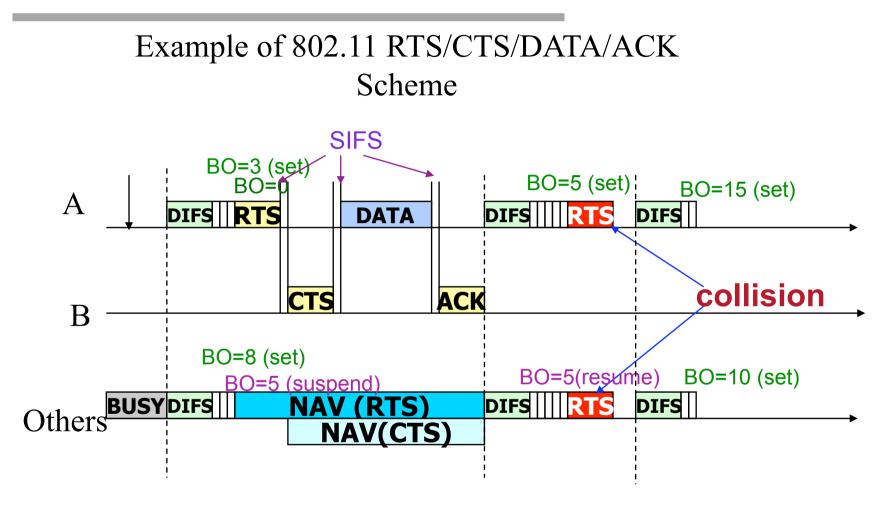


Relationship of different IFSs in 802.11



DIFS: DCF Interframe Space PIFS: PCF Interframe Space SIFS: Short Interframe Space





BO: backoff



Key parameters for wireless networks

	EasyRadio	RFMonolitics TR 1001	ChipCon CC1000	Lucent WLAN PC "Silver"
Frequency	868 MHz	868 MHz	868 MHz	2,4 GHz
Bit rate (Kbps)	19	115,2	76,8	11.000
Energy consumption				
send (mA)	17	12,0	25,4	284,0
receive (mA)	8	3,8	11,8	190,0
standby(µA)		0,7	30,0	10.000,0
switching time (µs)				
standby-transmit		16	2000	
receive-transmit		12	270	
standby-receive		518	2000	
transmit-receive		12	250	
transmit-standby		10		
receive-standby		10		



Sources of increased energy consumption:

active wait: If a node does not know when to expect a message, it must always remain in receive state.

overhearing: A node receives a message for which it is not the destination. Better: switch off the node during this time.

collisions: Energy which is used by sending a message during a collision is lost. The respective packet has to be resent completely. Collisions cannot be detected during sending.

protocolEvery additional measure like RTS/CTS or an acknowledge scheme increaseoverhead :the protocol overhead.

Dynamic Unbalanced load increases the probability of collisions (Thrashing). behaviour:



Big Problem: idle listening

Rx active power is often greater than Txactive power, due to the larger number of signal processing circuits that must be active

It's more power-efficient to blindly transmit than to blindly receive



Energy efficient protocols try to minimize the time of active listening!

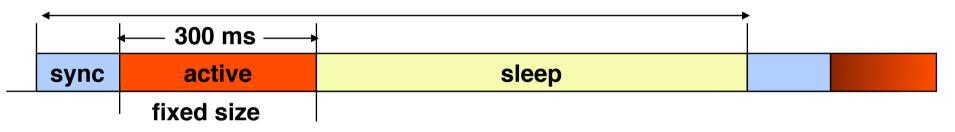
Approaches:

- Scheduling (TDMA)
- activation channel (narrow band additional channel)
- Preamble
- Adaptive schemes



Slotted protocols

Slot length: arbitrary but fixed (0,5 - 1 sec)



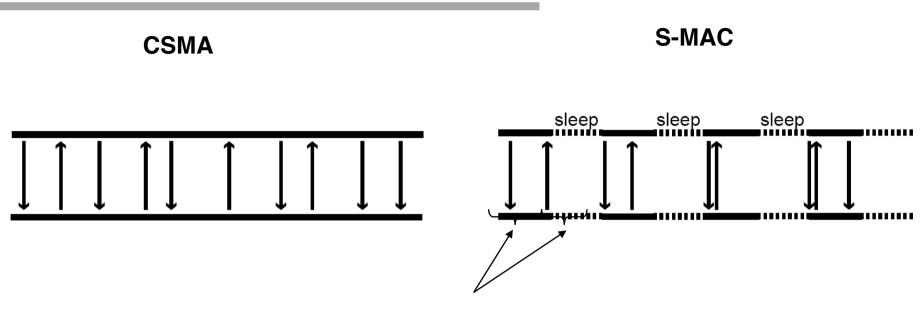
Example: S-MAC (Sensor -MAC) (Ye, Heideman, Estrin)

Nodes are organized in (virtual) clusters, which adopt a common slot format.

Variation T-MAC (Time-out MAC): Adaptively determining the relation between active and sleep perods. If the medium is idle the node can switch to sleep after a short interval.



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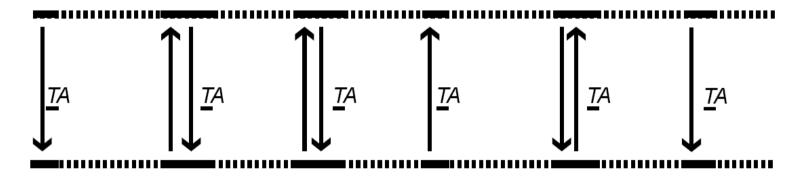


a priori fixed active and sleep intervals

During the activity periods the node must transmit local data + the messages which are relayed in the multi-hop network.

Problem with S-MAC: fixed periods





Determine the activity and sleep periods adaptivly.

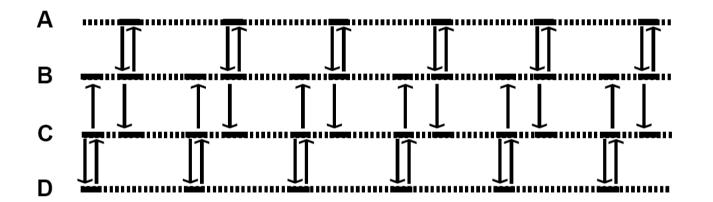
An activation event is given by:

- Alarm of a periodic timer;
- Reception of a message;
- Detection of some communication (also collisions are such events);
- Termination of the own transmision or of an ack.
- The knowledge that a communication by some neighbors has been terminated. (detected by overhearing)

All communication is performed in "bursts" at the start of the aktive period.



T-MAC: Communication over multiple clusters

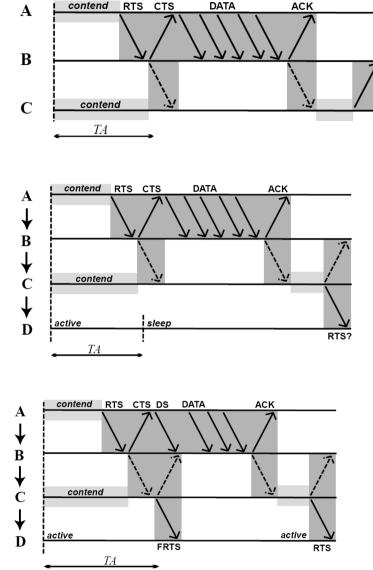


Communication between "virtual clusters" in T-MAC

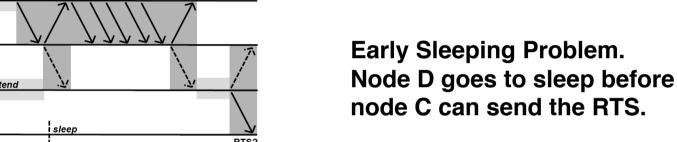
Messages to relay will be buffered. The size of the buffer determines the upper bounds of activity and sleep periods.



Further improvements: Eraly Sleeping Problem



Basic Cycle



Future Requests to Send (FRTS)

As the FRTS packet would disturb the data packet that follows the CTS, the data packet must be postponed for the duration of the FRTS packet. To prevent any other node from taking the channel during this time, the node that sent the initial RTS (node A in Figure 3.5) transmits a small Data-Send (DS) packet. After the DS packet, it must immediately send the normal data packet. Since the FRTS packet has the same size as a DS packet, it will collide with the DS packet, but not with the following data packet. The DS packet is lost, but that is no problem: it contains no useful information.

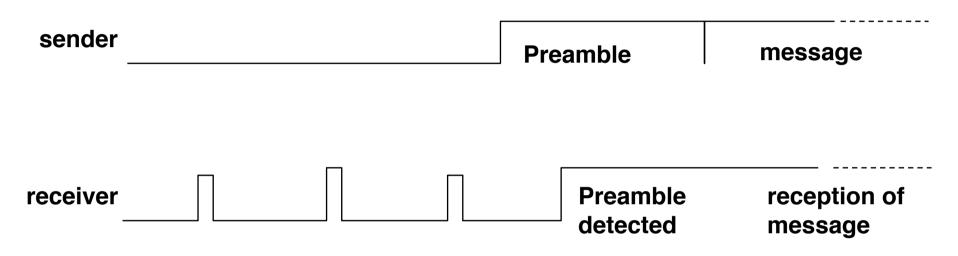
J.M. van Dam: An Adaptive Energy-E cient MAC Protocol for Wireless Sensor Networks June, 2003



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Variations: Low Power Listening

1.)



2.) Sender knows when the receiver is ready. Temporal coordination!

J. Hill, D. Culler: MICA: A wireless platform for deeply embedded networks. IEEE Micro 22(6), Nov. 2002

A. El-Hoiyi: Aloha with preamble sampling for sporadic traffic in ad-hoc wireless sensor networks, IEEE Int. Conf. on Comm. (ICC) New York, Apr. 2002

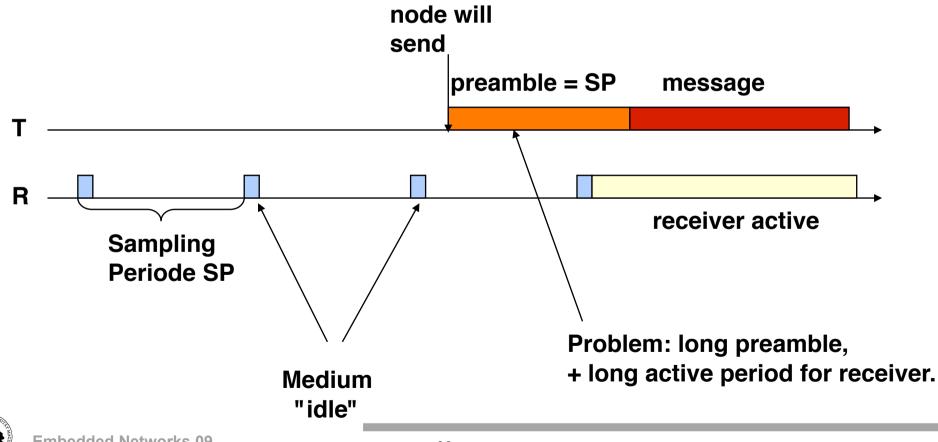


Low Power protocol: WiseMAC

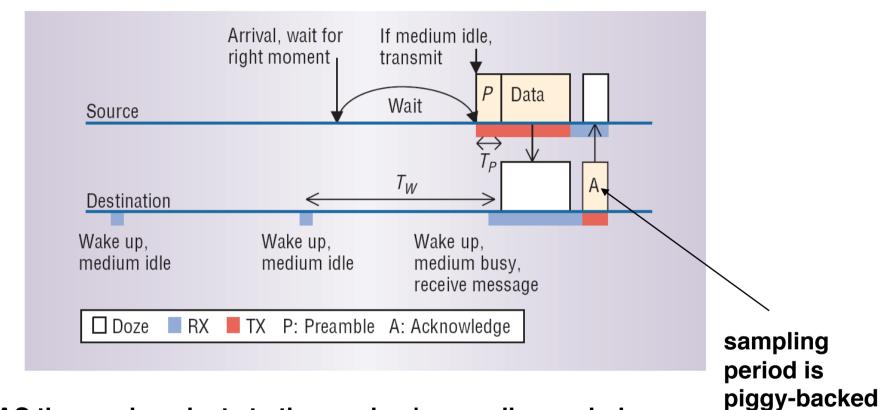
Christian C. Enz, Amre El-Hoivdi, Jean-Dominique Decotignie, Vincent Peiris (Swiss Center for Electronics and Microtechnology): WiseNET: An Ultralow-Power WirelessSensor Network Solution, IEEE Computer, August 2004

WiseMac exploits an optimized form of "Preamble Sampling"

Standard Preamble Sampling



Low Power protocol: WiseMAC



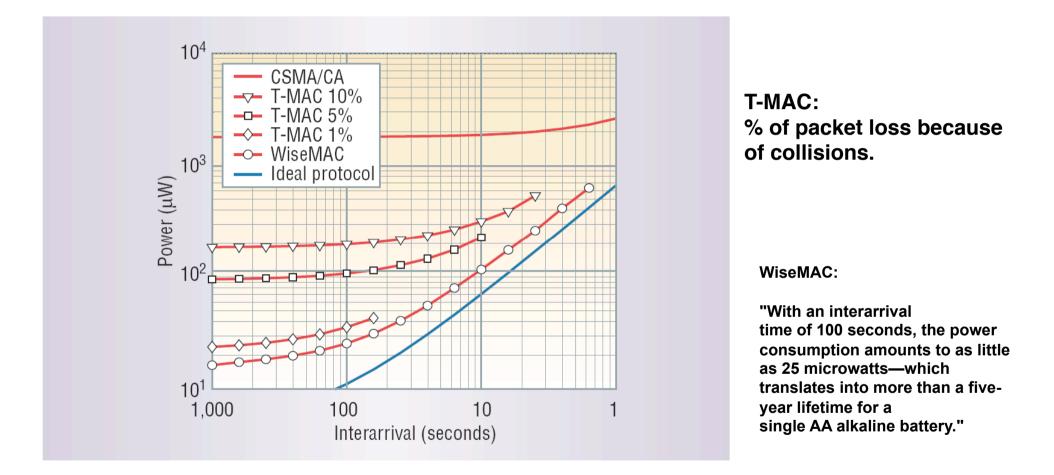
In WiseMAC the sender adapts to the receiver's sampling period.

Christian C. Enz, Amre El-Hoiydi, Jean-Dominique Decotignie, Vincent Peiris (Swiss Center for Electronics and Microtechnology): WiseNET: An Ultralow-Power WirelessSensor Network Solution, IEEE Computer, August 2004



in the ack.

Comparing Low Power Protols; every node has 8 neighbors.



Christian C. Enz, Amre El-Hoiydi, Jean-Dominique Decotignie, Vincent Peiris (Swiss Center for Electronics and Microtechnology): WiseNET: An Ultralow-Power WirelessSensor Network Solution, IEEE Computer, August 2004

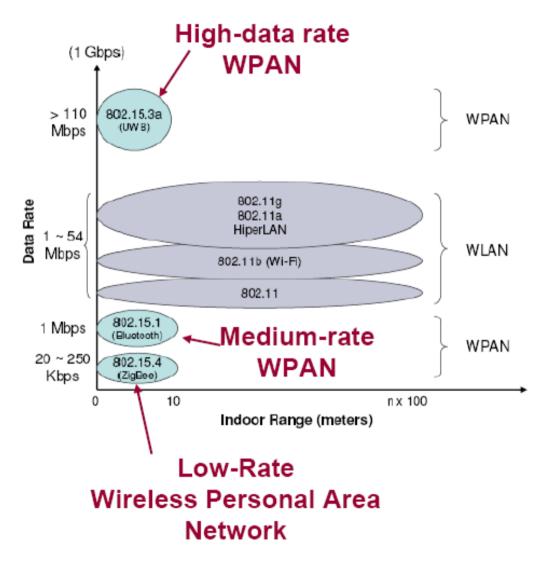
IEEE 802.15.4 WPAN

- 2 types of WPAN devices
- Network Topologies
- Architecture

Standard specifies:

- IEEE 802.15.4 PHY Layer
- IEEE 802.15.4 MAC Layer

ZigBee Alliance: provides for upper layer services







IEEE Standard for Information technology—Telecommunications and information exchange between systems—Local and metropolitan area networks Specific requirements—Part 15.4: Wireless Medium Access Control (MAC) and Physical Layer (PHY), Specifications for Low-Rate Wireless Personal Area Networks (LR-WPANs) Sponsor: LAN/MAN Standards Committee of the IEEE Computer Society Approved 12 May 2003. IEEE-SA Standards BoardJoe



Dvorak, Motorola, IEEE 802.15.4 and Zigbee Overview, 27.09.05



Steven Myers, Electrical and Computer Engineering University of Wisconsin Madison, ZigBee/IEEE 802.15.4



Jose Gutierrez "IEEE 802.15.4 Tutorial", Eaton Corporation, Jan. 2003.



Marco Naeve "IEEE 802.15.4 MAC Overview" Eaton Corporation, May 2004.



ZigBee

- Small packets over large network
- Data rate 250 kbps @2.4 GHz
- Allows up to 254 nodes
- Simplified protocol stack
- Used in time critical applications (15msec wake up time)
- Allows guaranteed transmission of critical messages
- Mostly Static networks with many, infrequently used devices

Bluetooth

- Large packets over small network
- Data rate is 1Mbps @2.4 GHz
- Allows up to 8 nodes in piconet setup
- More complex protocol stack
- Not so time critical (3sec wake up time)
- Ad-hoc networks
- File transfer



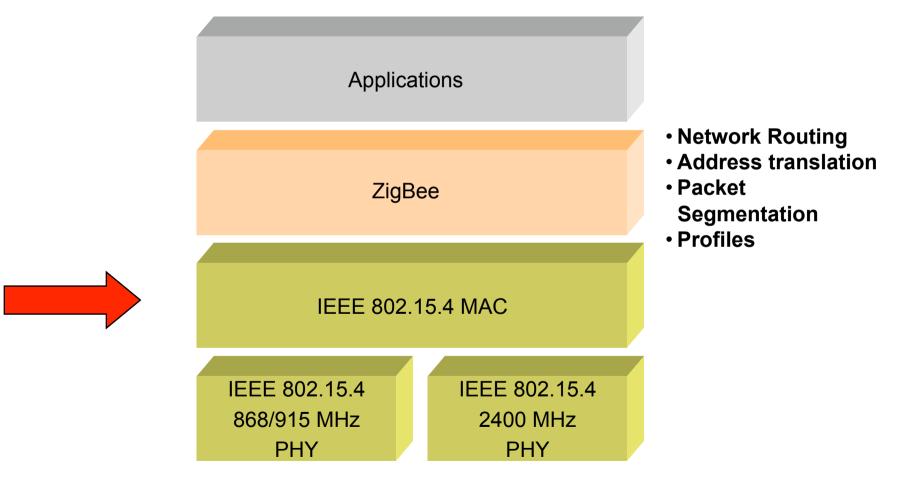
Wireless Technology Comparison Chart

Standard	Bandwidth	Power Consumption		Stronghold	Applications
Wi-Fi	Up to 54Mbps	400+mA TX, standby 20mA	100+KB	High data rate	Internet browsing, PC networking, file transfers
Bluetooth	1Mbps	40mA TX, standby 0.2mA	~100+KB	Interoperability, cable replacement	Wireless USB, handset, headset
ZigBee	250kbps	30mA TX, standby 356 μΑ	34KB /14KB	Long battery life, low cost	Remote control, battery-operated products, sensors



J. Kaiser, IVS-EOS

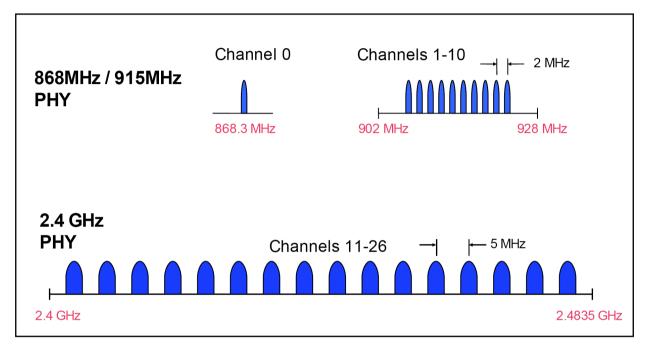
802.15.4 Architecture



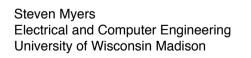


Provides two services to physical layer management entity (PLME)

- PHY data service
- exchange data packets between MAC and PHY
- PHY management service interface
- Clear channel assessment (CCA)
 - 3 methods:
 - Energy above threshold,
 - Carrier sense only, or
 - Carrier sense w/ energy above threshold
- Energy detection (ED)
 - Used by network layer (channel selection)
- Link Quality Indication (LQI)
 - Used by higher layers
 - Uses ED and/or SNR estimate



802.15.4 Channel Assignment





PHY packet format and MAC frame format

Types of MAC Frames:

- Data Frame
- Beacon Frame
- Acknowledgment Frame
 MAC Command Frame

			neader		100101
sync. header	SOP	phys. header	MAC protocol data unit (MPDU)		
	delimit.		phys. service data unit (PSDU)		
Octets: 4	1	1		0-127]
			Y		

MAC

hoodor

PHY Packet Fields:

- Preamble (32 bits) synchronization
- Start of Packet Delimiter (8 bits)
- PHY Header (8 bits) PSDU length
- PSDU (0 to 1016 bits) Data field

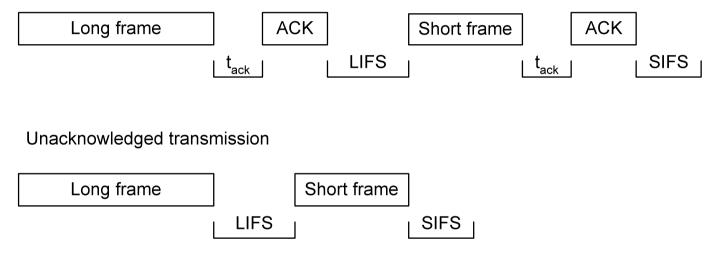


MAC

footer

PAYLOAD

Acknowledged transmission



aTurnaroundTime ≤ t_{ack} ≤ (aTurnaroundTime (12 symbols) + aUnitBackoffPeriod (20 symbols)) LIFS > aMaxLIFSPeriod (40 symbols) SIFS > aMacSIFSPeriod (12 symbols)

For frames < aMaxSIFSFrameSize use short inter-frame spacing (SIFS) For frames > aMaxSIFSFrameSize use long inter-frame spacing (LIFS)



Provides two services to the MAC sublayer management entity (MLME)

MAC data service

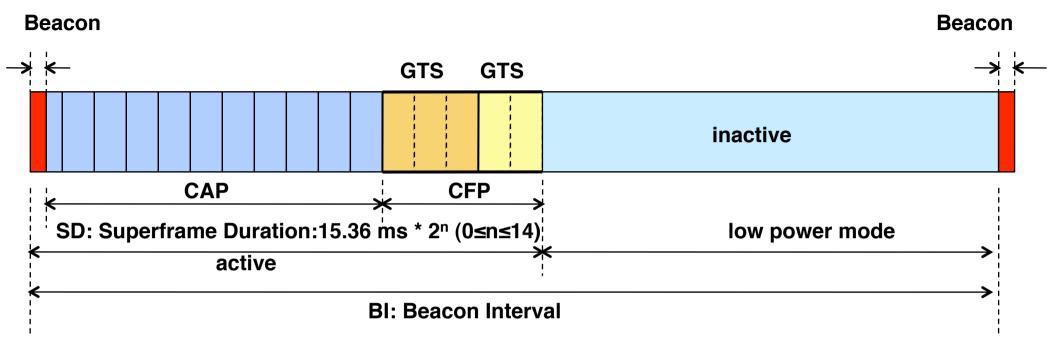
• Enables transmission and reception of MAC protocol data units (MPDU) across PHY data service

MAC management service

- Beacon management
- Channel access
- GTS management
- Frame validation
- ACK frame delivery
- Association and disassociation



Optional Superframe Structure



Beacon: sent by PAN coordinator in the first slot of the superframe. Contains network information, frame structure and notification of pending node messages.

Contention Access Period (CAP): Communication using slotted CSMA-CA Contention Free Period (CFP): Guaranteed time slots (GTS) given by coordinator (no CSMA) Beacon Order (BO): Describes the interval at which the coordinator shall transmit its beacon frames. Superframe Order (SO): Describes the length of the active portion of the superframe.



Arbitration

Slotted CSMA-CA:

Used in superframe structure Backoff periods are aligned with superframe slot boundaries of PAN coordinator

Used in CAP, must locate boundary of the next backoff period to transmit data

Un-slotted CSMA-CA:

Non beacon enabled network Backoff periods are not synchronized between devices



Each device has three variables:

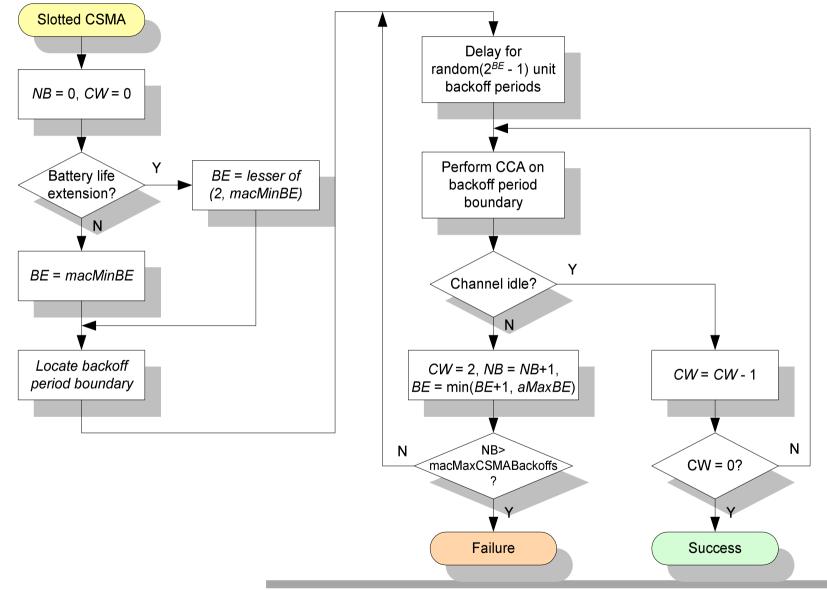
NB is the number of times the CSMA-CA was required to backoff while attempting a current transmission.

CW is the contention window length, which defines the number of backoff periods that needs to be clear of activity before a transmission can start.

BE is the **backoff exponent**, which is related to how many backoff periods a device shall wait before attempting to assess the channel.

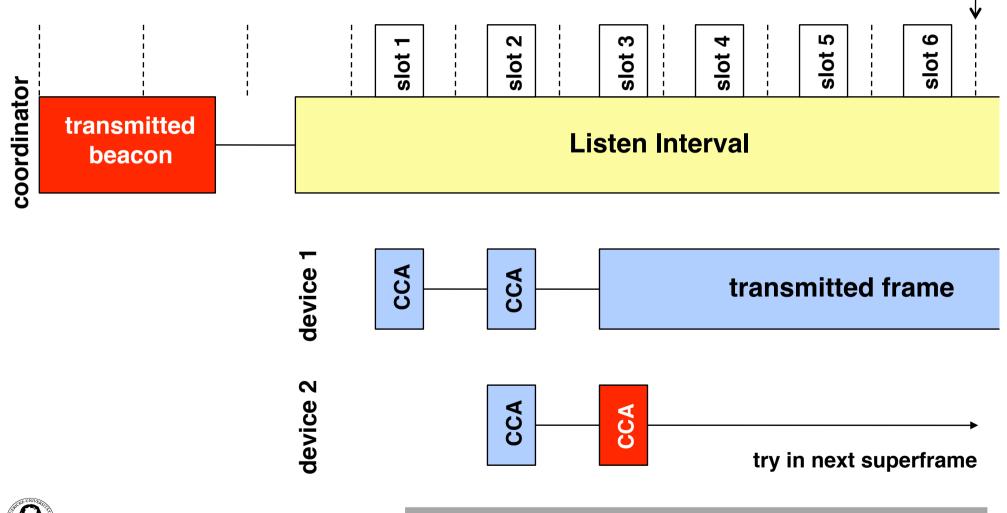


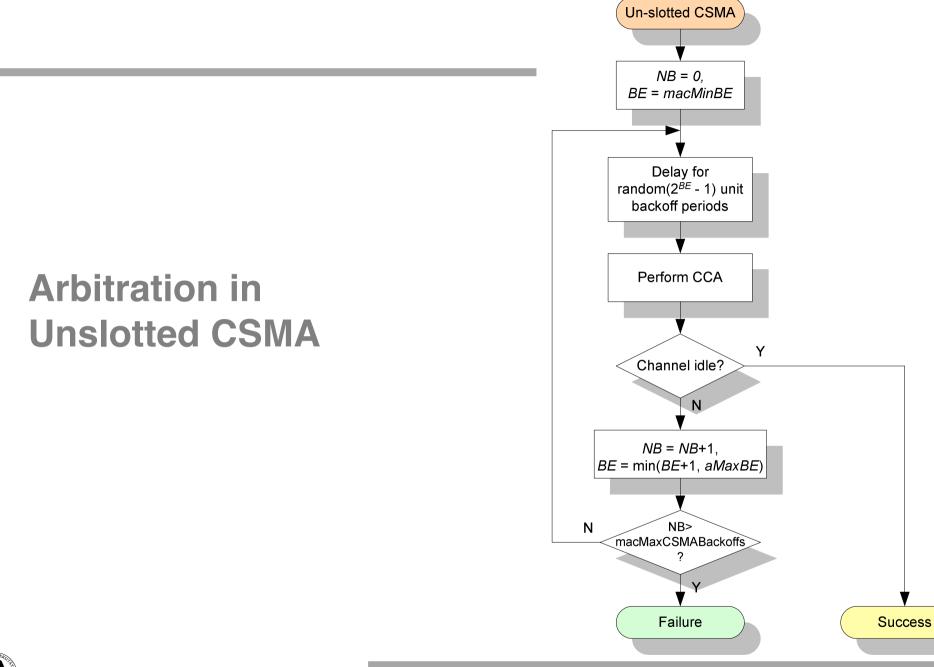
Arbitration in Slotted CSMA

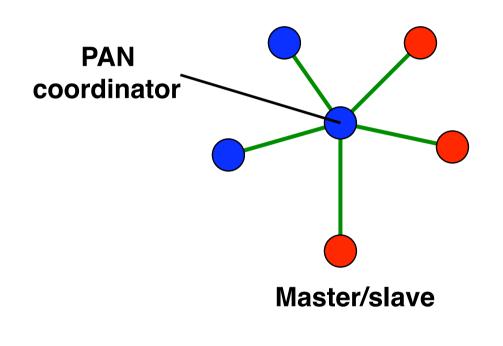


Battery Life Extension (BLE)

Turn-Off Point if no signal detected







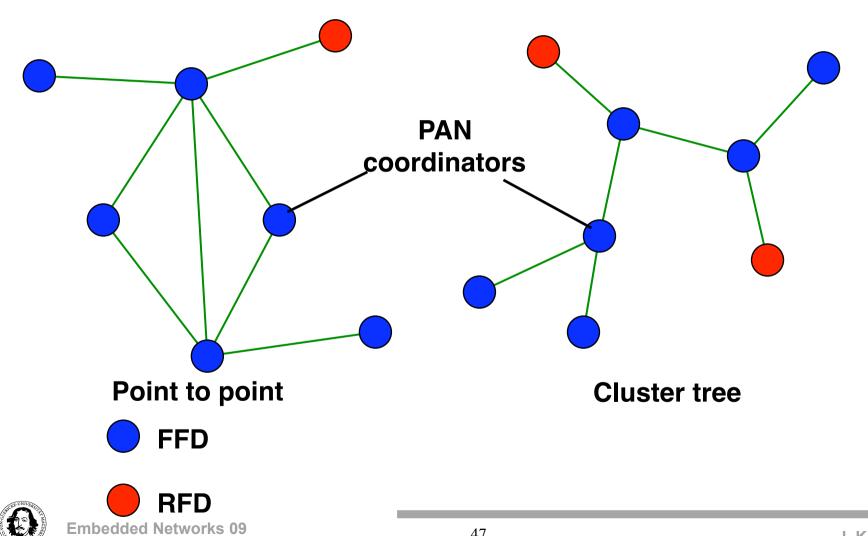






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Peer-Peer Topology



Clustered stars

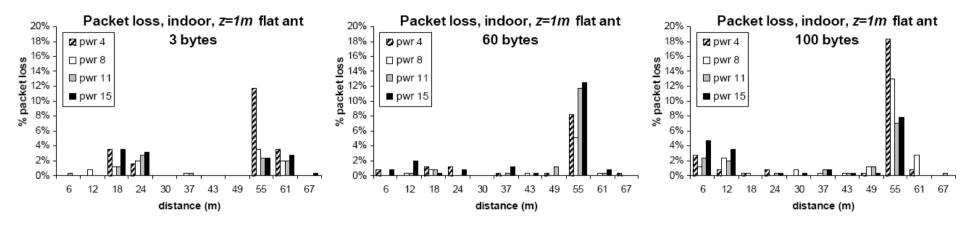
FFD

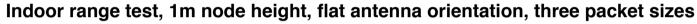


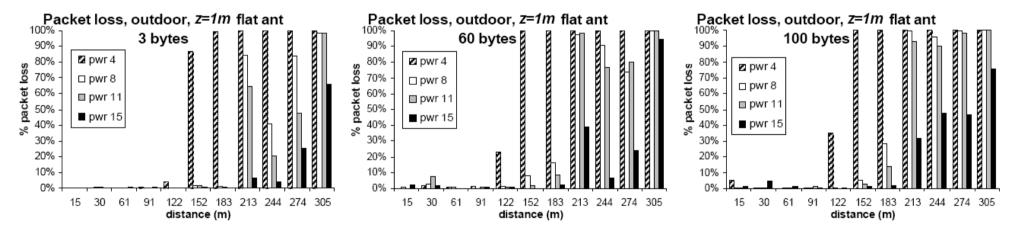


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Clustered stars - for example, cluster nodes exist between rooms of a hotel and each room has a star network for control.







Outdoor range test, 1m node height, flat antenna orientation, three packet sizes

Steven Myers, Suman Banerjee, Seapahn Megerian, and Miodrag Potkonjak

Experimental Investigation of IEEE 802.15.4 Transmission Power Control and Interference Minimization

4th Annual IEEE Communications Society Conference on Sensor, Mesh and Ad Hoc Communications and Networks, 2007. SECON '07, San Diego, CA, June 2007



Embedded Networks

- o Introduction
- o Models of communication
- o Dependability and fault-tolerance
 - * Attributes and measures of Dependability
 - * Basic techniques of Fault-Tolerance
- o Time, Order and Clock synchronization
- o The physical network layer
- o Protocols for timely and reliable communication
 - * Controller Area Network (CAN-Bus)
 - * Time Triggered Protokoll (TTP/C)
 - * Byteflight, Flexray
 - * LIN, TTP/A
 - * Token protocols
- o Sensornets
 - * Protocols for wireless communication
 - * Energy-efficient MAC-protocols

